

IN THE CLAIMS

Please amend the claims as follows:

Claim 1. (Currently Amended) A vibratory mechanism comprising:
a first eccentric weight being rotatably supported within a housing;
a second eccentric weight being coaxially rotatable with said first eccentric weight;
an inner shaft operatively connected to said first eccentric weight;
an outer shaft being coaxially positioned about said inner shaft and operatively connected to said second eccentric weight; and
a planetary gearbox operatively connected to said inner shaft and said outer shaft, said planetary gearbox being adapted to index said second eccentric weight relative to said first eccentric weight.

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Claim 2. (Currently Amended) The vibratory mechanism in claim 1, including a motor connected to said planetary gearbox to supply rotational input to said first eccentric weight and said second eccentric weight.

Claim 3. (Currently Amended) The vibratory mechanism in claim 1, wherein said planetary gearbox has first and second planetary arrangements.

Claim 4. (Currently Amended) The vibratory mechanism in claim 3 wherein said planetary gearbox includes:

an input sun gear coaxial with said inner shaft and driven by said motor;
an input planetary gear set that meshes with said input sun gear;
a fixed ring gear that meshes with said input planetary gear set;
an output planetary gear set, said input planetary gear set is connected to said output planetary gear set;
a movable ring gear which meshes with said output planetary gear set; and

an output sun gear that meshes with said output planetary gear set and drives said outer shaft.

Claim 5. (Previously Presented) The vibratory mechanism in claim 4, further including a pinion gear operatively connected to a phase control device for rotating said movable ring gear to index said second eccentric weight relative to said first eccentric weight.

Claim 6. (Original) The vibratory mechanism in claim 5, wherein said phase control device is a phase motor.

Claim 7. (Original) The vibratory mechanism in claim 5, wherein said phase control device is rack and two opposing linear actuators.

Claim 8. (Original) The vibratory mechanism in claim 5, wherein said phase control device is a hand wheel.

Claim 9. (Original) The vibratory mechanism recited in claim 1, further including a speed sensor mounted on said inner shaft and another speed sensor mounted on said outer shaft.

Claim 10. (Currently Amended) The vibratory mechanism recited in claim 9, further including:

a motor connected to said gearbox for rotating said inner and said outer shafts;
~~a speed sensor connected with each of said inner shaft and said outer shaft;~~
a sensor connected with a phase control device; and
a controller connected to and utilizing an output from said speed sensors and said sensor, to control operation of said ~~vibrator propel~~ motor and said phase control device.

Claim 11. (Currently Amended) A work machine, comprising:
a compacting drum supporting said work machine;
a vibratory mechanism coaxially positioned within said compacting drum;
said vibratory mechanism including;
a first eccentric weight being rotatably supported within a housing;
a second eccentric weight being coaxially rotatable with said first eccentric weight;
an inner shaft operatively connected to said first eccentric weight;
an outer shaft being coaxially positioned about said inner shaft and operatively connected to said second eccentric weight; and
a planetary gearbox operatively connected to said inner shaft and said outer shaft, said gearbox being adapted to index said second eccentric weight relative to said first eccentric weight.

Claim 12. (Currently Amended) The work machine in claim 11, including:
a first power source;
a propel motor connected to said compacting drum and operatively connected with said first power source;
a second power source;
a motor connected to the planetary gearbox to rotate said first and said second eccentric weights, said motor being operatively connected to said second power source.

Claim 13. (Original) The work machine in claim 12, wherein said first and second power sources are hydraulic pumps.

Claim 14. (Original) The work machine in claim 12, wherein said first and second power sources are electric generators.

Claim 15. (Currently Amended)) The work machine in claim 12 wherein said planetary gearbox includes:

an input sun gear coaxial with by said inner shaft and driven by said motor;
an input planetary gear set that meshes with said input sun gear;
a fixed ring gear that meshes with said input planetary gear set;
an output planetary gear set, said input planetary gear set is connected to said output planetary gear set;
a movable ring gear which meshes with said output planetary gear set; and
an output sun gear that meshes with said output planetary gear set and drives said outer shaft in rotation.

Claim 16. (Previously Presented) The work machine in claim 15, further including:

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a pinion gear; and
a phase control device operatively connected to said pinion gear for rotating said movable ring gear to index said second eccentric weight relative to said first eccentric weight.

Claim 17. (Previously Presented) The work machine in claim 16, wherein said phase control device is a phase motor.

Claim 18. (Previously Presented) The work machine in claim 16, wherein said phase control device is a rack and two opposing linear actuators.

Claim 19. (Previously Presented) The work machine in claim 16, further including a speed sensor connected with said inner shaft and another speed sensor connected with said outer shaft.

Claim 20. (Currently Amended) The work machine recited in claim 16, ~~further including a pinion gear is operatively connected to~~ wherein said phase control device is a phase motor for rotating said movable ring gear to index said second eccentric weight

relative to said first eccentric weight, and an output shaft of said phase motor having a rotary sensor attached therewith.

Claim 21. (Currently Amended) The work machine recited in claim 16, further including:

~~a motor for rotating said through shaft;~~

a speed sensor connected with each of said inner shaft and said outer shaft;

a phase position sensor connected with each of said inner shaft and said outer shaft; and

a controller ~~that uses an output of~~ connected to and utilizing an output from a one of said speed sensors and said phase position sensors to control operation of said motor and said phase control device

Claim 22. (Original) The work machine recited in claim 21, further including an accelerometer for outputting signals indicative of an amount of vibration created by rotation of said first and second eccentric weights, wherein said controller controls operation of said motor and said phase control device based on the output signals of said accelerometer.

Claim 23. (Currently Amended) A method for operating a vibratory mechanism of a work machine having a planetary gearbox for adjusting a vibration amplitude, the gearbox includes an inner shaft connected with a first eccentric weight and an outer shaft, surrounding at least portion of the inner shaft, is connected with a second eccentric weight, said method comprising:

operating the planetary gearbox to change a phase difference between the first eccentric weight and the second eccentric weight to change the vibration amplitude.

Claims 24 and 25. (Canceled)

Claim 26. (Original) The method recited in claim 23, wherein said operating step is controlled by a computer controller based on at least one of a ground speed of the